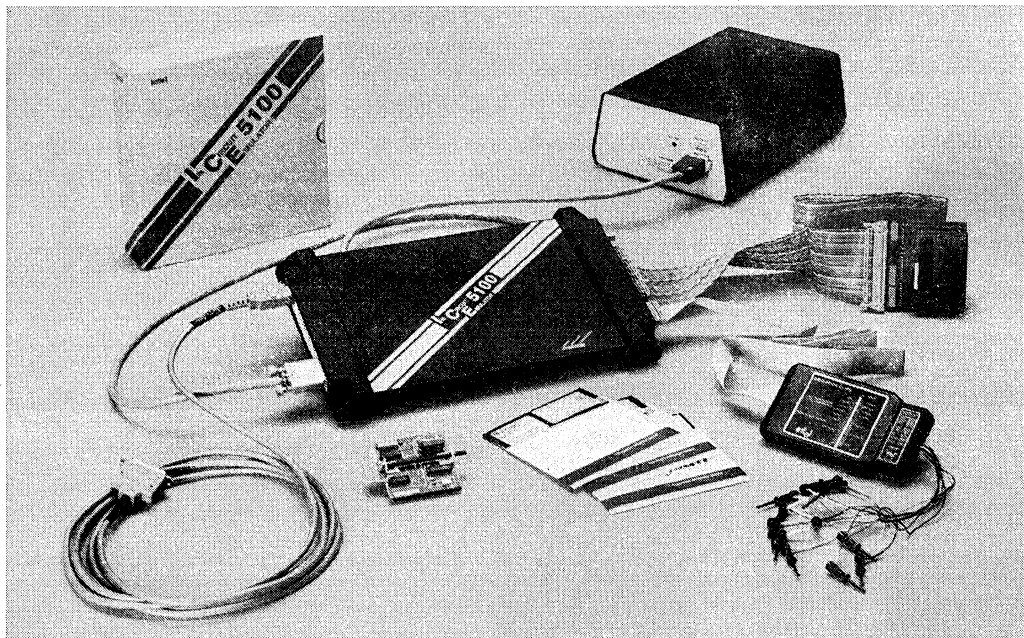




## ICE™-5100/252 In-Circuit Emulator for the MCS®-51 Family of Microcontrollers

- Real-time Emulation of Selected MCS®-51 Microcontroller Components at Speeds up to 16 MHz
- 64 KB of Mappable High-Speed Emulation Memory
- 254 24-Bit Frames of Trace Memory (16 Bits Trace Program Execution Addresses and 8 Bits Trace External Events)
- Serial Link to Intel Series III/IV or IBM\* PC AT and PC XT (and PC-DOS Compatibles)
- ASM-51 and PL/M-51 Language Support
- Built-In CRT-Oriented Text Editor
- Symbolic Debugging Enables Access to Memory Locations and Program Variables
- Four Address Breakpoints Plus In-Range, Out-of-Range, and Page Breaks
- Equipped with the Integrated Command Directory (ICD™) that Provides
  - On-Line Help
  - Syntax Guidance and Checking
  - Dynamic Command-Entry
  - Error Checking
  - Command Recall
- On-Line Disassembler and Single-Line Assembler to Help with Code Patching

The ICE™-5100/252 In-Circuit Emulator is a high-level, interactive debugger that is used to develop and test the hardware and software of a target system based on the MCS-51 family of microcontrollers. The ICE-5100/252 emulator can be serially linked to an Intellec® Series III/IV or an IBM PC AT or PC XT. The emulator can communicate with the host system at standard baud rates up to 19.2K. The design of the emulator supports selected MCS-51 microcontroller components at speeds up to 16 MHz.



\*IBM is a registered trademark of International Business Machines Corporation.

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## PRODUCT OVERVIEW

The ICE-5100/252 emulator provides full emulation support for the MCS-51 family members listed in Table 1.

The ICE-5100/252 emulator enables hardware and software development to proceed simultaneously. With the ICE-5100/252 emulator, prototype hardware can be added to the system as it is designed and software can be developed prior to the completion of the hardware prototype. Software and hardware integration can occur while the product is being developed.

The ICE-5100/252 emulator assists four stages of development :

- Software debugging
- Hardware debugging
- System integration
- System test

### Software Debugging

The ICE-5100/252 emulator can be operated without being connected to the target system or before any of the user's hardware is available (provided external data RAM is not needed). In this stand-alone mode, the ICE-5100/252 emulator can be used to facilitate program development.

### Hardware Debugging

The ICE-5100/252 emulator's AC/DC parametric characteristics match the microcontroller's; its full-speed operation makes it a valuable tool for debugging hardware, including time-critical serial port, timer, and external interrupt interfaces.

## System Integration

Integration of software and hardware can begin when the emulator is plugged into the microcontroller socket of the prototype system hardware. Hardware can be added, modified, and tested immediately. As each section of the user's hardware is completed, it can be added to the prototype. Thus, the hardware and software can be system tested in real-time operation as it becomes available.

## System Test

When the prototype is complete, it is tested with the final version of the system software. The ICE-5100/252 emulator is then used for real-time emulation of the microcontroller to debug the system as a completed unit.

The final product verification test can be performed using the ROM orEPROM version of the microcontroller. Thus, the ICE-5100/252 emulator provides the ability to debug a prototype or production system at any stage in its development without introducing extraneous hardware or software test tools.

## PHYSICAL DESCRIPTION

The ICE-5100/252 emulator consists of the following components (see Figure 1):

- Power supply
- AC and DC power cables
- Controller pod
- Serial cable (host-specific)
- User probe assembly (consisting of processor module and user cable)
- Crystal power accessory (CPA)

**Table 1. MCS®-51 Family Support Offered by the ICETM-5100/252 Emulator**

Part	On-Chip Program Memory	On-Chip Data Memory
8031	None	128 bytes
80C31	None	128 bytes
8032	None	256 bytes
8051	4 KB-ROM	128 bytes
80C51	4 KB-ROM	128 bytes
8052	8 KB-ROM	256 bytes
80C252	None	256 bytes
83C252	8 KB-ROM	256 bytes
8751	4 KB-EPROM	128 bytes
87C51	4 KB-EPROM	128 bytes
8752	8 KB-EPROM	256 bytes
87C252	8 KB-EPROM	256 bytes

- 40-pin DIP target adaptor
- Clips assembly
- Software (includes the ICE-5100/252 emulator software, diagnostic software, and tutorial).

The controller pod contains 64 KB of emulation memory, a 254-frame trace buffer, and the control processor. In addition, the controller pod houses a BNC connector that can be used to connect up to 10 multi-ICE compatible systems together for synchronous GO and BREAK emulation.

The serial cable connects the host system to the controller pod. The serial cable supports a subset of the RS-232C signals.

The user probe assembly consists of a user cable and a processor module. The processor module houses the emulation processor and provides the logic needed to support mapped memory, breakpoints, emulation, interrogation, and modification of registers and memory. The target adaptor connects to the processor module and provides an electrical and mechanical interface to the target microcontroller socket.

The crystal power accessory (CPA) is a small, detachable board that connects to the controller pod and enables you to run the ICE-5100/252 emulator in a stand-alone (loop-back) mode of operation. In stand-alone mode, the target adaptor plugs into the socket on the CPA; the CPA then supplies clock and power to the user probe.

The clips assembly enables the user to trace external events. Eight bits of data are gathered on the rising edge of  $\overline{\text{PSEN}}$  during opcode fetches. The clips information can be displayed using the CLIPS option with the PRINT command.

The ICE-5100/252 emulator software supports mnemonics, object file formats, and symbolic references generated by Intel's ASM-51 and PL/M-51 programming languages. Along with the ICE-5100/252 emulator software is a customer confidence test disk with diagnostic routines that check the operation of the hardware.

The on-line tutorial is written in the ICE-5100/252 command language. Thus, the user is able to interact with and use the ICE-5100/252 emulator while executing the tutorial.

A comprehensive set of documentation is included with the ICE-5100/252 emulator.

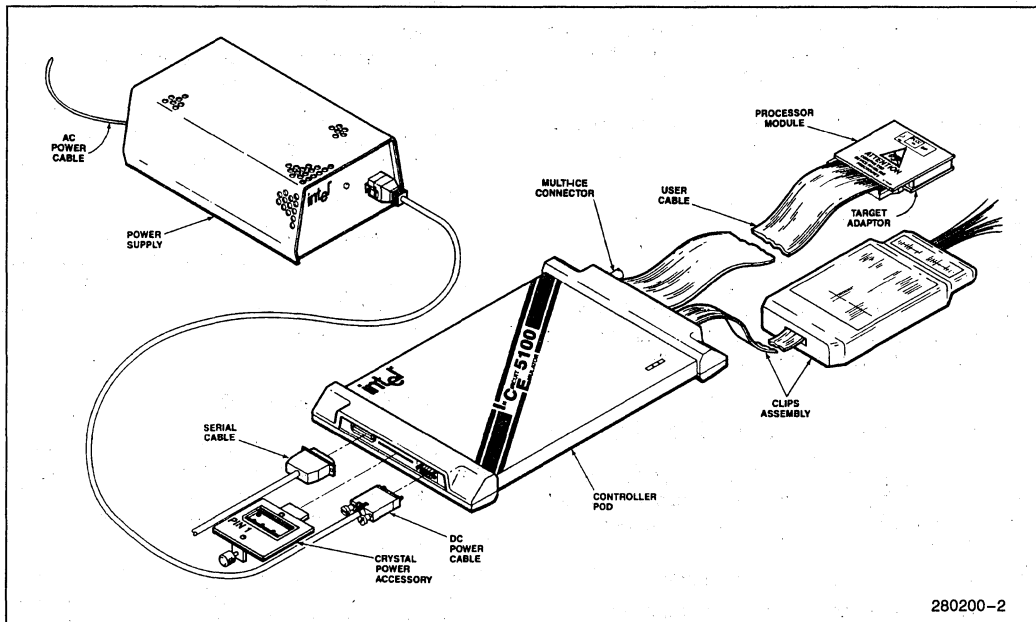


Figure 1. The ICE™-5100/252 Emulator Hardware

## ICE™-5100/252 EMULATOR FEATURES

The ICE-5100/252 emulator has been created to assist a product designer in developing, debugging and testing designs incorporating the MCS-51 family of microcontrollers. The following sections detail some of the ICE-5100/252 emulator features.

### Processor Selection

The ICE-5100/252 emulator enables you to emulate the microcontrollers listed in Table 1. Selecting a processor type changes the following characteristics to match the microcontroller selected:

- Internal RAM size
- Internal ROM size
- Idle and power down mode enable
- Special function register symbolic map
- Memory map
- Latched or unlatched  $\overline{EA}$
- Serial port framing error detection

### Emulation

Emulation is the controlled execution of the user's software in the target hardware or in an artificial hardware environment that duplicates the microcontroller of the target system. Emulation is a transparent process that happens in real-time. The execution of the user software is facilitated through the ICE-5100/252 command language.

### Memory Mapping

There is 64 KB of memory that can be mapped to the CODE memory space in 4 KB blocks on 4K boundaries. By mapping memory to the ICE-5100/252 emulator, software development can proceed before user hardware is available.

### Memory Examination and Modification

The memory space for the MCS-51 component(s) and its target hardware is fully accessible through the emulator. The microcontroller has four physically distinct memory spaces:

- CODE — references program memory
- IDATA — references internal data memory
- RDATA — references special function register memory

- XDATA — references external data memory

ICE-5100/252 emulator commands that access memory must use one of the special prefixes (e.g., CODE) to specify the memory space in which the partition lies.

The microcontroller's special function registers and register bits can be accessed mnemonically (e.g., DPL, TCON, CY) with the ICE-5100/252 emulator software.

Data can be displayed or modified in one of three bases: hexadecimal, decimal, or binary and in ASCII and unsigned integer formats. Program code can be disassembled and displayed as ASM-51 assembler mnemonics. Code can be modified with standard ASM-51 statements using the built-in single-line assembler.

Symbolic debugging is used to specify memory locations by their symbolic references. A symbolic reference is a procedure name, line number, or label in the user program that corresponds to a location. Using symbolics to reference program locations is a mnemonic way of accessing the program.

Some typical symbolic functions include:

- Changing or inspecting the value of a program variable by using its symbolic name to access the memory location.
- Defining break and trace events using symbolic references.
- Referencing variables as primitive data types. The primitive data types are ADDRESS, BIT, BOOLEAN, BYTE, CHAR (character), and WORD.

The ICE-5100/252 emulator maintains a virtual symbol table for program symbols making it possible for the table to exist without fitting entirely into host RAM memory. The size of the table is constrained only by the disk capacity.

### Breakpoint Specifications

Breakpoints are used to halt a user program in order to examine the effect of the program's execution on the target system. The ICE-5100/252 emulator supports three different types of break specifications in real-time mode:

- Specific address break — Specifying a single address point at which emulation is to be stopped. This address can be an executable program statement or a program label.

- Range break — An arbitrary range of addresses can be specified to halt emulation. Program execution within or outside the range halts emulation.
- Page break — Up to 256 page breaks can be specified. A page break is defined as a range of addresses that is 256-bytes long and begins on a 256-byte address boundary.

Break registers are user-defined debug definitions used to create and store breakpoint definitions. Break registers can contain multiple breakpoint definitions and can optionally call debug procedures when emulation halts.

## Trace Specifications

Tracing can be triggered using specifications similar to those used for breaking. Normally, the ICE-5100/252 emulator traces program activity while the user program is executing. With a trace specification, tracing can be triggered to occur only when specific conditions are met during execution. Up to 254 24-bit frames of trace information are collected in a buffer during emulation. Sixteen of the 24 bits trace instruction execution addresses, and 8 bits capture external events (CLIPS).

The trace buffer display is similar to an ASM-51 program listing as shown in Figure 2. The PRINT command enables the user to selectively display the contents of the trace buffer. The user has the option of displaying the clips information as well as disassembled instructions.

## Procedures

Debugging procedures (PROCS) are a user-named group of ICE-5100/252 commands that are executed sequentially. PROCS can simulate missing hardware or software, collect debug information, execute high-level software patches, or make troubleshooting decisions. PROCS can be copied to text files on disk, then included from the file into the command sequence in later test sessions.

PROCS can also serve as programmable diagnostics, implementing ICE-5100/252 emulator commands or user-defined definitions for special purposes.

## On-Line Syntax Menu

A special syntax menu, called the Integrated Command Directory (ICD), aids in creating syntactically correct command lines. Figure 3 shows an example of the ICD and how it changes to reflect the options available for the GO command.

## HELP

The HELP command provides assistance with ICE-5100/252 emulation commands through the host system terminal. On-line HELP is available for the ICE-5100/252 emulator commands shown in Figure 4.

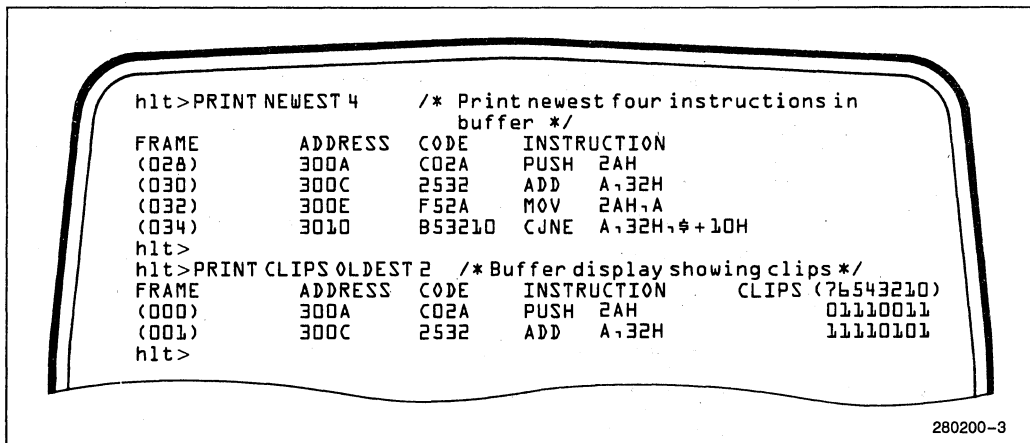


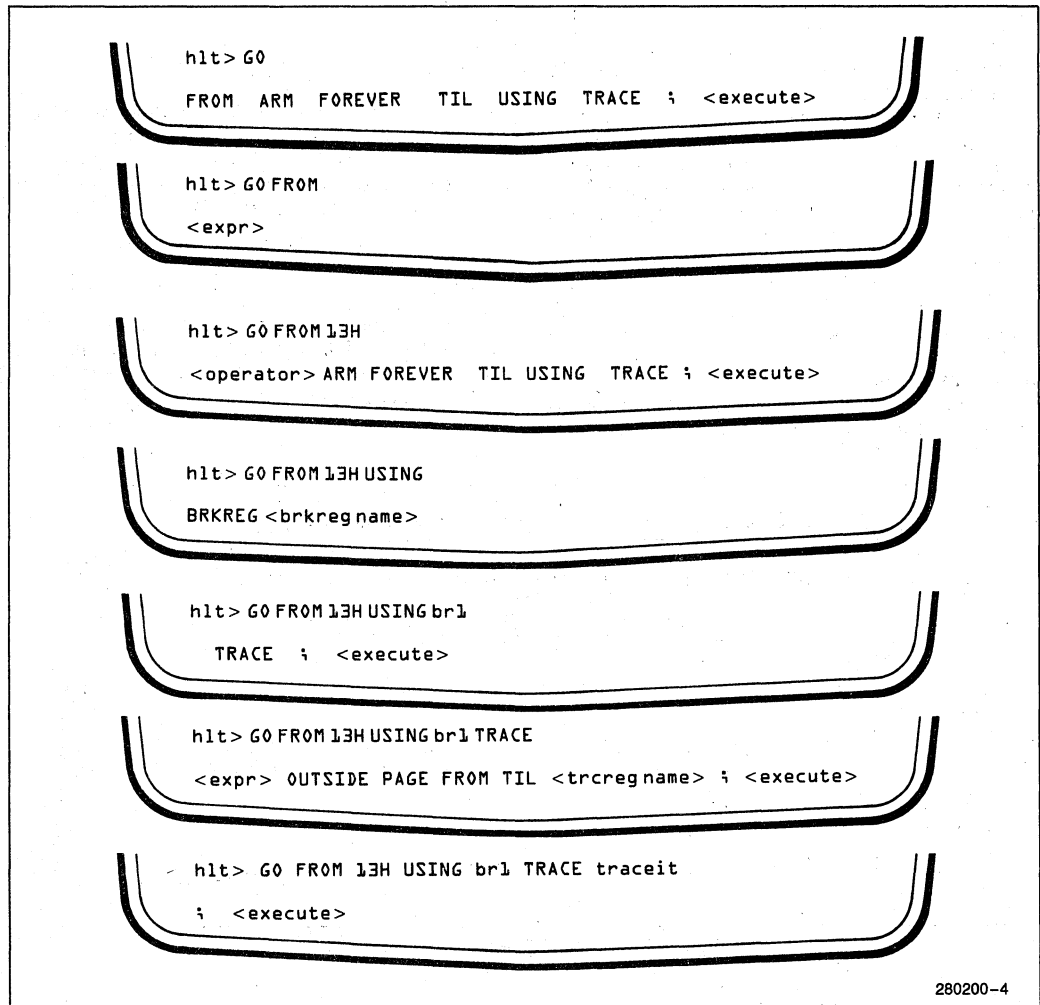
Figure 2. Selected Trace Buffer Displays

## DESIGN CONSIDERATIONS

The height of the processor module and the target adaptor may pose a problem for multiple board target systems that need to be debugged. Allow at least 1½ inches (3.8 cm) of space between boards to fit the processor module and target adaptor. Figure 5 shows the dimensions of the processor module.

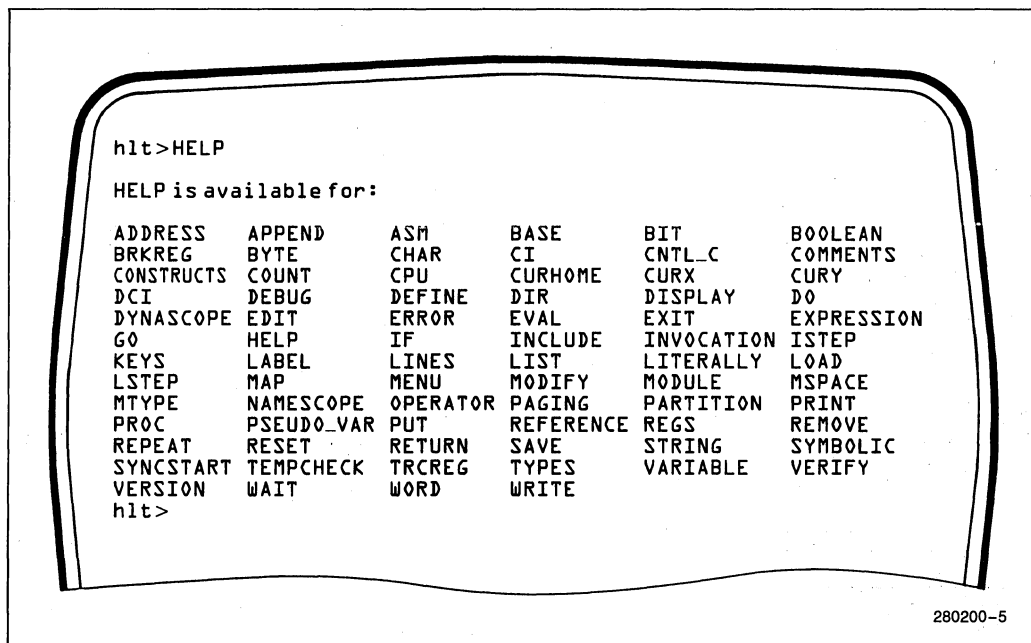
The following are limitations of the A-step emulation processor and should be kept in mind when using the ICE 5100 emulator. These problems will be fixed with the B-step version.

- The stack pointer of the emulation processor does not operate properly when pointing to addresses beyond 07FH. Internal data memory above 07FH can be addressed using standard indirect instructions.
- Execution of user programs that contain interrupt routines will cause incorrect data to be stored in the trace buffer. When an interrupt occurs, the next instruction to be executed is placed into the trace buffer before it is actually executed. Following completion of the interrupt routine, the instruction is executed and again placed into the trace buffer. There is no workaround for this bug at this time.

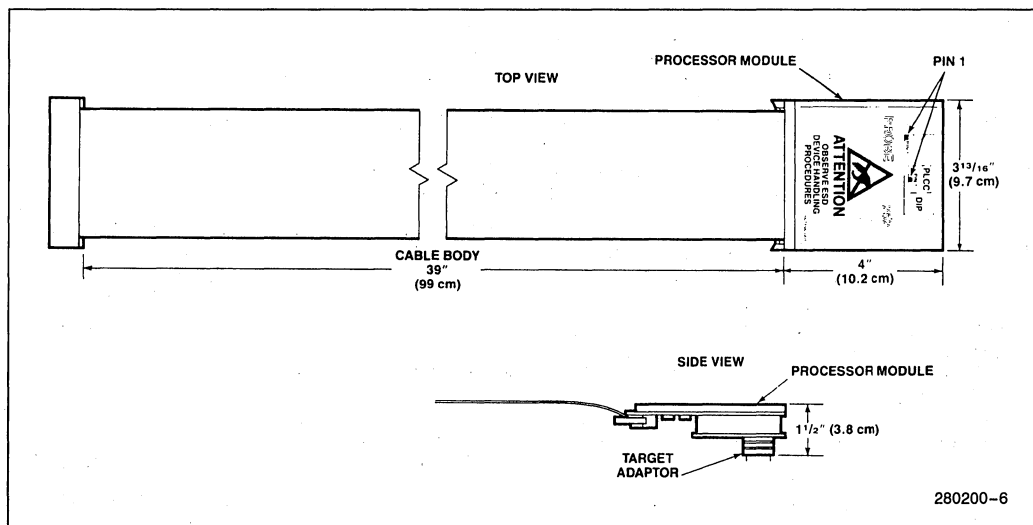


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Figure 3. The Integrated Command Directory for the GO Command



**Figure 4. HELP Menu**



### Figure 5. Processor Module Dimensions

## ELECTRICAL CONSIDERATIONS

The emulation processor's user-pin timings and loadings are identical to the 80C252 component except as follows.

**Maximum Operating ICC (ma)\***

V <sub>CC</sub>	4V	5V	6V
Frequency			
0.5 MHz	2.4	3.3	4.5
3.5 MHz	6.5	8.5	11.0
8.0 MHz	13.0	17.0	21.0
12.0 MHz	18.0	24.0	30.0
16.0 MHz	23.0	31.0	39.0

\*ICC is measured with all output pins disconnected. XTAL1 driven with TCLCH, TCHCL = 10 ns, V<sub>il</sub> = V<sub>SS</sub> + .5V, V<sub>ih</sub> = V<sub>CC</sub> - .5V. XTAL2 not connected. EA = RST = Port0 = V<sub>CC</sub>.

**Maximum Idle ICC (ma)\***

V <sub>CC</sub>	4V	5V	6V
Frequency			
0.5 MHz	0.9	1.4	1.8
3.5 MHz	1.6	2.4	3.3
8.0 MHz	2.7	4.1	5.5
12.0 MHz	3.7	5.6	7.5
16.0 MHz	4.7	7.1	9.5

\*Idle ICC is measured with all output pins disconnected. XTAL1 driven with TCLCH, TCHCL = 10ns, V<sub>il</sub> = V<sub>SS</sub> + .5V, V<sub>ih</sub> = V<sub>CC</sub> - .5V. XTAL2 not connected. EA = PORT0 = V<sub>CC</sub>, RST = V<sub>CC</sub>, internal clock to PCA gated off.

- Up to 25 pf of additional pin capacitance is contributed by the processor module and target adaptor assemblies.
- Pin 31, EA, has approximately 32 pf of additional capacitance loading due to sensing circuitry.
- Pins 18 and 19, XTAL1 and XTAL2 respectively, have approximately 15-16 pf of additional capacitance when configured for crystal operation.

## Emulating HMOS Components

The ICE-5100/252 emulator is based on a CHMOS emulation processor. There are minor differences between how the ICE-5100/252 emulator supports CHMOS and HMOS designs as shown in Table 2.

Refer to the Mirocontroller Handbook, order number 210918, for further information on CHMOS and HMOS design considerations.

## HOST REQUIREMENTS

- IBM PC AT or PC XT (or PC-DOS compatible) with 512 KB of RAM and a hard disk running under the DOS 3.0 (or later) operating system.
- Intellec Series III/IV Microcomputer Development System running under the ISIS or iNDX operating system respectively, with at least 512 KB of application memory resident.

Disk drives — Dual floppy or one hard disk and one floppy drive required.

## ICE-252 SYSTEM SOFTWARE PACKAGE

- ICE-5100/252 emulator software
- ICE-5100/252 confidence tests
- ICE-5100/252 tutorial software

## SYSTEM PERFORMANCE

### Memory

Mappable high-speed emulation code memory	Min 0 KB Max 64 KB	Mappable to user or ICE-5100/252 emulator memory in 4 KB blocks on 4 KB boundaries.
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Trace Buffer      254 x 24 bits frames

**Table 2. CHMOS and HMOS Design Differences**

Chip Function	HMOS Component 8031	CHMOS Component 80C31
RST trigger threshold	2.5V	70% V <sub>CC</sub> (3.5V @ V <sub>CC</sub> = 5V)
RST input impedance	4K — 10K ohms	50K — 150K ohms
Port I <sub>il</sub>	— 800μA	— 50 μA
Clock threshold	2.5V	70% V <sub>CC</sub> (3.5V @ V <sub>CC</sub> = 5V)



**Virtual Symbol Table** A maximum of 61 KB of host memory space is available for the virtual symbol table (VST). The rest of the VST resides on disk and is paged in and out as needed.

## PHYSICAL CHARACTERISTICS

### Controller Pod

Width 8 $\frac{1}{4}$ " (21 cm)  
Height 1 $\frac{1}{2}$ " (3.8 cm)  
Depth 13 $\frac{1}{2}$ " (34.3 cm)  
Weight 4 lbs (1.85 kg)

### User Cable

3' (.944 m)

### Processor Module

(with target adaptor attached)

Width 3 $\frac{13}{16}$ " (9.7 cm)  
Length 4" (10.2 cm)  
Height 1 $\frac{1}{2}$ " (3.8 cm)

### Power Supply

Width 7 $\frac{5}{8}$ " (18.1 cm)  
Height 4" (10.06 cm)  
Depth 11" (27.97 cm)  
Weight 15 lbs (6.1 kg)

### Serial Cable

12' (3.6 m)

## ELECTRICAL CHARACTERISTICS

### Power Supply

100 - 120V or 200 - 240V (selectable)  
50 - 60 Hz  
2 amps (AC max) - 120V  
1 amp (AC max) - 240V

## ENVIRONMENTAL CHARACTERISTICS

Operating temperature +10° C to +40°C (37.5°F to 104°F)

Operating Humidity Maximum of 85% relative humidity, non-condensing

## ORDERING INFORMATION

### Emulator Hardware and Software

#### Order Code Description

**I252KITAD** Consists of: ICE-5100/252 user probe assembly, power supply and cables, serial cables, target adaptor, CPA, ICE-5100 controller pod, software, and documentation for use with an IBM PC AT or PC XT. Kit also includes the 8051 Software Development Package and the AEDIT text editor for use on DOS systems. [Requires software license.]

**I252KITD** Same as the I252KITAD package except this one does not include the 8051 Software Development Package or AEDIT text editor. [Requires software license.]

**I252KITAS** Consists of: ICE-5100/252 user probe assembly, power supply and cables, serial cables, target adaptor, CPA, ICE-5100 controller pod, software, and documentation for use with Intel hosts (Series III, IV). Kit also includes the 8051 Software Development Package and the AEDIT text editor for use on Series III and Series IV. [Requires software license.]

**I252KITS** Same as the I252KITAS package except this one does not include the 8051 Software Development Package or AEDIT text editor. [Requires software license.]

### Software Only

#### Order Code Description

**SA252D** Kit contains the software for the host, probe, diagnostic, and tutorial on 5 $\frac{1}{4}$ -inch disks for use on an IBM PC AT or PC XT (requires DOS 3.0 or later). [Requires software license.]

**SA252S** Kit contains the software for the host, probe, diagnostic, and tutorial on 8-inch disks (both single-density and double-density) for use on a Series III, and on 5¼-inch disks for use on a Series IV. [Requires software license].

#### Other Useful Intel MCS-51 Debug and Development Support Products

##### Order Code Description

**D86ASM51** 8051 Software Development Package (DOS version) — Consists of the ASM-51 macro assembler which gives symbolic access to 8051 hardware features, the RL51 linker and relocater program that links modules generated by ASM-51, CONV51 which enables software written for the MCS-48 family to be up-graded to run on the 8051, and the LIB51 Librarian which programmers can use to create and maintain libraries of software object modules. Use with the DOS operating system (version 3.0 or later).

**D86PLM51** PL/M-51 Software Package (DOS version) — Consists of the PL/M-51 compiler that provides high-level programming language support, the LIB51 utility that creates and maintains libraries of software object modules, and the RL51 linker and relocater program that links modules generated by ASM-51 and PL/M-51 and locates the linked object modules to absolute memory locations. Use with the DOS operating system (version 3.0 or later).

**I86ASM51** 8051 Software Development Package (ISIS version) — Same as the D86ASM51 package except this one is for use with the Series III and Series IV.

**I86PLM51** PL/M-51 Software Package — Same as the D86PLM51 package except this one is for use with the Series III and Series IV.

**D86EDIEU** AEDIT text editor for use with the DOS operating system.